3500/46M Hydro Monitor

Bently Nevada* Asset Condition Monitoring



Description

The 3500/46M Hydro Monitor is a 4-channel monitor that accepts input from proximity, seismic and air gap sensors. The monitor conditions the signal to provide various vibration and position measurements, and compares the conditioned signals with user-programmable alarms. Hydro Radial Vibration channels combine the shaft gap movement with the NX amplitude to provide a measurement to alarm on shear-pin failure. The user can program each channel of the 3500/46M using the 3500 Rack Configuration Software to perform any of the following functions:

- Hydro Radial Vibration
- Hvdro Air Gap
- Hydro Velocity
- Hydro Acceleration
- Hydro Thrust
- Multimode Hydro RV
- Multimode Air Gap
- Multimode Hydro Velocity
- Multimode Thrust
- Multimode Acceleration
- Hydro Stator End Winding (SEW)

Note: The monitor channels are programmed in pairs. Each channel may have separate or identical configurations.

The purpose of the 3500/46M monitor is to provide:

- 1. Machinery protection by continuously comparing monitored parameters against configured alarm set points to drive alarms.
- 2. Essential machine management information for both operations and maintenance personnel.

Note: Due to the nature of high amplitude, low frequency velocity events, the Hydro Velocity channel type cannot be used for automated machinery protection. Its purpose is to provide early warning of pending machinery problems and to assist in diagnosing machinery problems.

Each channel, depending on configuration, typically conditions its input signal into various parameters called "proportional values". The user can configure Alert set points for various active proportional values and Danger set points for up to two active proportional values.

The user can configure multimode channels to have up to eight sets of alarm parameters (Alert and Danger set points and alarm time delays). The configuration of each set can be for a specific machine mode, and the monitor can switch to a specific set as the machine changes modes. This is done via contacts on multimode I/O modules or by software commands through a communications gateway.











Hydro Velocity and Multimode **Specifications Hydro Velocity:** Inputs 20mV/mm/s (508mV/in/s). Inputs **Hydro Thrust** and Multimode Signal **Thrust** Accepts 1 to 4 proximity, air gap, 3.94mV/µm (100mV/mil) or velocity or acceleration sensor signals. 7.87mV/µm (200mV/mil) or Input 11.22mV/µm (285mV/mil). **Impedance** Hydro Prox/Velom **Acceleration** 1/0 and and Multimode Multimode **Acceleration** Prox/Velom $1.02 \text{mV/m/s}^2 (10 \text{mV/g}) \text{ or }$ 1/0 2.55mV/m/s² (25mV/g) or $10k\Omega$ for Prox/Accel. Hydro SEW $3.5M\Omega$ for Velomitor. 10.19mV/m/s² (100mV/g) Multimode Positive Input 1/0 **Outputs** $50k\Omega$. **Front Panel** Power **LEDs** Consumption **OK LED** 7.7 watts, typical. Indicates when the 3500/46M is Sensitivity operating properly. Hydro Radial TX/RX LED Vibration and Indicates when the 3500/46M is Multimode communicating with other Hydro RV: modules in the 3500 rack. 0.79mV/µm (20mV/mil) or **Bypass LED** 3.94mV/ μ m (100mV/mil) or Indicates when the 3500/46M is in 7.87mV/µm (200mV/mil). Bypass Mode. Hydro Air Gap **Buffered** and Multimode Transducer Air Gap **Outputs** 0.20mV/µm (5mV/mil) or The front of each monitor has one coaxial connector for each 0.22mV/µm (5.6mV/mil) or channel. Each connector is short-0.49mV/µm (12.5mV/mil) or circuit protected. 0.55mV/µm (14mV/mil). Output **Impedance**

550Ω.

Transducer Power Supply

Prox/Velom I/O and Multimode Prox/Velom I/O

-23Vdc nominal at 43 mA max.

Multimode Positive Input I/O

+23Vdc nominal at 23mA max.

Recorder

+4 to +20mA. Output is proportional to monitor full-scale. One output is provided for each channel. Monitor operation is unaffected by short circuits on recorder outputs.

Voltage Compliance (current output)

0 to +12Vdc range across load. Load resistance is 0 to 600Ω .

Resolution

0.3662µA per bit

±0.25% error at room

temperature ±0.7% error over

temperature.

Update rate is 100ms or less.

Signal Conditioning

Note: Specified at +25 °C (+77 °F) unless otherwise

noted.

Hydro Radial Vibration and Multimode Hydro RV Frequency Response

Direct filter

0.25X rotor speed to 500Hz. Rotor speed is 25 to 1,500cpm. Gap filter

-3 dB at 0.05Hz.

Not 1X filter

0.25 to 128 times rotor speed. Constant Q notch filter. Minimum rejection in stopband of -50dB.

1X and NX Vector filter

Constant Q Filter. Minimum rejection in stopband of –50dB. The N value in NX may be set between 2 and 20.

Note: 1X & NX Vector, Not 1X and Composite parameters are valid for machine speeds of 25 cpm to 1,500 cpm.

Composite

NX amplitude multiplied by the percent change in gap from its zero position. Specific for detecting "Shear Pin" failure.

Hydro Radial Vibration and Multimode Hydro RV

Direct and Gap

Within $\pm 0.33\%$ of full-scale typical, $\pm 1\%$ maximum.

1X and NX

Within ±0.33% of full-scale typical, ±1% 1X maximum.

±3% NX maximum.

Not 1X

±1% of full-scale typical.

±3% maximum.

Composite

 $\pm 1\%$ of full-scale typical.

Hydro Air Gap and Multimode Air Gap Description

Instantaneous Air Gap

> Provides instantaneous gap measurements when the polepassing rate slows to less than one pole/second.

Average Air Gap

The monitor measures each pole gap and averages the values for all poles together over one revolution.

Minimum Air Gap

The minimum pole gap value in a revolution.

Maximum Air Gap

The maximum pole gap value in a revolution.

Min Air Gap Pole Number

> The pole number detected with the minimum gap value in a revolution.

Max Air Gap Pole Number

The pole number detected with the maximum gap value in a revolution.

Note: All values except Instantaneous Air Gap are valid when the poles passing rate is between 1 and 200 poles/second. Hydro Air Gap and Multimode Air Gap Accuracy Average Air Gap, Minimum Air Gap, Maximum Air Gap

Within ±0.33% of full scale typical, ±1% maximum.

Hydro Velocity and Multimode Hydro Velocity Frequency Response

Bias

Low-pass filter.

Low Mode: -3dB at 0.02 Hz. High Mode: -3dB at 0.07 Hz.

Direct

Low Mode: 0.1875 to 343.75 Hz, -

3dB.

High Mode: 0. 75 to 1375 Hz, -3dB.

1X and 2X Vector filter

Constant Q Filter. Minimum rejection in stopband of –51dB.

Low Mode: Valid for machine speeds of 60 to 6,000cpm.

High Mode: Valid for machine speeds of 60 to 24,600cpm.

Hydro Velocity and Multimode Hydro Velocity Filter Quality

High-pass

4-pole (80dB per decade, 24dB

per octave).

Low-pass

2-pole (40dB per decade, 12dB

per octave).

Hydro Velocity and Multimode **Hydro Velocity Accuracy**

Direct, 1X Amplitude, 2X **Amplitude**

> Within ±1% of full-scale typical, ±2% maximum. Exclusive of filters.

-3dB at 1.2Hz.

-3dB at 0.41Hz.

Within ±0.33% of full-scale

typical, ±1% maximum.

Hydro Thrust and Multimode

Response

Thrust Frequency

Direct filter

Gap filter

Hydro Thrust and Multimode

Thrust

Accuracy Direct

Hydro Acceleration and Multimode Acceleration Frequency

Response Bias filter

Not OK filter

1X & 2X Vector filter

> Constant Q Filter. Minimum rejection in stopband of -51dB.

> Low-pass filter. -3dB at 0.01Hz.

Low-pass filter. -3dB at 2400Hz.

Valid for machine speeds of 60cpm to 60,000cpm.

The following table represents the frequency ranges for the monitor under different options using the Multimode Acceleration Channel Type:

Output Type	Non- Integrated (Hz)	Integrated (Hz)
RMS	10 to 30,000	10 to 20,000
Peak	3 to 30,000	10 to 20,000

Hydro Acceleration and Multimode Acceleration **Filter Quality**

High-pass

4-pole (80dB per decade, 24dB

per octave).

Low-pass

4-pole (80dB per decade, 24dB per octave).

Hydro Acceleration and Multimode Acceleration

Direct, 1X Amplitude, 2X **Amplitude**

> Within ±0.33% of full scale typical, ±1% maximum. Exclusive of

filters.

Frequency Response

Hydro SEW

Direct

5.0Hz to 800Hz (-3dB corners)

Bias Voltage

DC to 0.05Hz (-3dB)

Pole Pass **Amplitude**

> 2x line frequency (100Hz or 120Hz). Constant O filter (O=20). Minimum rejection in stop band of

-60dB

Direct Resultant

5.0Hz to 800Hz (-3dB corners). Resultant of both X and Y axis

inputs.

Pole Pass Resultant

> 2x line frequency (100Hz or 120Hz). Constant Q filter (Q=20). Minimum rejection in stop band of -60dB. Resultant of both X and Y

axis inputs.

Accuracy

Direct

±1% of Full Scale maximum.

Bias Voltage

±1% of Full Scale maximum.

Pole Pass **Amplitude**

> ±2% of full-scale typical, ±3% maximum.

Direct Resultant

±1% of full-scale typical, ±2% maximum.

Pole Pass Resultant

> ±2% of full-scale typical, ±3% maximum.

Alarms

Alarm Setpoints

The user can set Alert levels for various values measured by the monitor and Danger set points for up to two of the values measured by the monitor using

configuration software. Alarms are adjustable from 0 to 100% of full-scale for each measured

value. The exception is when the full-scale range exceeds the range of the transducer. In this case, the range of the transducer will limit the set point of the transducer. Accuracy of alarms are to within 0.13% of the desired value.

Hydro Radial **Vibration**

> Direct, Gap, Not 1X Amplitude, 1X Amplitude, NX Amplitude, Composite, 1X Phase Lag, NX Phase Lag.

Multimode Hydro RV

> Direct, Gap, Not 1X Amplitude, 1X Amplitude, NX Amplitude, Composite, 1X Phase Lag.

Hydro Air Gap and Multimode Air Gap

Average Air Gap, Minimum Air

Gap.

Hydro Velocity and Multimode **Hydro Velocity**

> Direct, 1X Amplitude, 2X Amplitude, 1X Phase Lag, 2X

Phase Laa.

Thrust Direct, Gap.

Hydro Acceleration and Multimode **Acceleration**

Hydro Thrust

and Multimode

Direct, 1X Amplitude, 2X Amplitude, 1X Phase Lag, 2X

Phase Lag.

Hydro SEW

Direct, Pole Pass Amplitude, Direct Resultant, Pole Pass Resultant.

Alarm Time Delays Gap Pole Number, Maximum Air Gap Pole Number, and Mode.

The user can program Alarm delays using software. For multimode channels, the user can set delays for each proportional value having alarm set points. For standard channels, the user sets one alert and danger delay for the channel.

Hydro Velocity

Direct, Bias, 1X Amplitude, 1X Phase Lag, 2X Amplitude, and 2X Phase Lag.

Alert

Multimode Hydro Velocity

> Direct, Bias, 1X Amplitude, 1X Phase Lag, 2X Amplitude, 2X Phase Lag and Mode.

From 1 to 400 seconds, in 1 second intervals.

Hydro Thrust

Direct and Gap.

Danger

From 1 to 400 seconds, in 1 second intervals.

Multimode Thrust

Direct, Gap and Mode.

Proportional Values

Proportional values are measurements used to monitor the machine. The 3500/46M Monitor provides the following proportional values: Hydro Acceleration

> Direct, Bias, 1X Amplitude, 1X Phase Lag, 2X Amplitude, 2X, and Phase Lag.

Hydro Radial Vibration

> Direct, Gap, 1X Amplitude, 1X Phase Lag, NX Amplitude, NX Phase Lag, Not 1X Amplitude, and Composite Amplitude.

Multimode Acceleration

> Direct, Bias, 1X Amplitude, 1X Phase Lag, 2X Amplitude, 2X Phase Lag, and Mode.

Multimode Hydro RV

> Direct, Gap, 1X Amplitude, 1X Phase Lag, NX Amplitude, Not 1X Amplitude, Composite Amplitude, and Mode.

Hydro SEW

Direct, Bias Voltage, Pole Pass Amplitude, Direct Resultant, and Pole Pass Resultant.

Hydro Air Gap

Multimode Air

Gap

Average Air Gap, Instantaneous Air Gap, Minimum Air Gap, Maximum Air Gap, Minimum Air Gap Pole Number, Maximum Air Gap Pole Number. **Environmental Limits**

Operating Temperature

-30 °C to +65 °C (-22 °F to +150 °F).

n Air Storage Temperature

-40 °C to +85 °C (-40 °F to +185 °F).

Average Air Gap, Instantaneous

Air Gap, Minimum Air Gap, Maximum Air Gap, Minimum Air Humidity

95%, noncondensing.

Compliance and Certifications

EMC

Standards:

EN 61000-6-2 Immunity for Industrial

Environments

EN 55011/CISPR 11 ISM Equipment

EN 61000-6-4 Emissions for Industrial

Environments

European Community Directives:

EMC Directive 2004/108/EC

Electrical Safety

Standards:

EN 61010-1

European Community Directives: 2006/95/EC Low Voltage

Hazardous Area Approvals

North American **Approval Option** (01)

When used with I/O module ordering options with internal barriers:

Ex nC [ia] IIC: Class I, Div 1

AEx nC [ia] IIC: Class 1, Zone 2/0

Groups A, B, C, D

T4 @ Ta = -20 °C to +65 °C

(-4 °F to +150 °F)

per drawing 138547

When used with I/O module ordering options without internal barriers:

Ex nC [L] IIC: Class I, Div 2

AEx nC IIC: Class 1, Div 2

Groups A, B, C, D

T4 @ Ta = $-20 \,^{\circ}$ C to $+65 \,^{\circ}$ C

(-4 °F to +150 °F)

per drawing 149243

ATEX Approval Option (02)

For Selected Ordering Options with ATEX/CSA agency approvals:

For ATEX agency approval ordering options with internal barriers:

⟨E_x⟩ II 3/(1) G

Ex nC[ia Ga] IIC T4 Gc

T4 @ Ta = -20° C to $+65^{\circ}$ C

 $(-4^{\circ}F \text{ to } +150^{\circ}F)$

For ATEX agency approval ordering options without internal barriers:

⟨E_x⟩ II 3/(3) G

Ex nC[nL Gc] IIC T4 Gc

T4 @ Ta = -20° C to $+65^{\circ}$ C

 $(-4^{\circ}F \text{ to } +150^{\circ}F)$

Brazil **Approval Option** (02)

For Selected Ordering Options with ATEX/North American agency approvals:

Ex nC [ia Ga] IICT4 Gc Ex nC [ic Gc] IIC T4 Gc

South Africa

Approval Option (02)

For Selected Ordering Options with ATEX/North American agency approvals:

Ex nCAL [ia] IIC T4

Ex nCAL [L] IIC T4

T4 @ Ta = -20 °C to +65 °C

(-4 °F to +150 °F)

For further certification and approvals information please visit the following website:

www.ge-mcs.com/bently

Physical Hydro Air Gap **Applications Monitor Module** 3500/46M Module Firmware -**Dimensions** Version 2.09 (Height x Width 3500/01 Software - Version 3.40 x Depth) 3500/02 Software – Version 2.30 241.3 mm x 24.4 mm x 241.8 mm 3500/03 Software - Version 1.30 $(9.50 \text{ in } \times 0.96 \text{ in } \times 9.52 \text{ in}).$ **Hydro Velocity** Weight **Applications** 0.91 kg (2.0 lb). 3500/46M Module Firmware -I/O Module Version 2.10 **Dimensions** 3500/01 Software - Version 3.70 (Height x Width 3500/02 Software - Version 2.50 x Depth) 3500/03 Software - Version 1.50 241.3 mm x 24.4 mm x 99.1 mm Hydro $(9.50 \text{ in } \times 0.96 \text{ in } \times 3.90 \text{ in}).$ Acceleration **Applications** Weight 3500/46M Module Firmware -0.20 kg (0.44 lb) Version 2.40 3500/01 Software - Version 4.40 **Rack Space Requirements Hydro Thrust Monitor Module Applications** 1 full-height front slot. 3500/46M Module Firmware -Version 2.40 I/O Modules 3500/01 Software - Version 4.40 1 full-height rear slot. Multimode **Applications Ordering Considerations** For Hydro RV, Air Gap, Hydro Velocity, Thrust, and Acceleration General applications: The 3500/46M Module requires the following (or later) firmware, 3500/46M Module Firmware and software revisions: Version 2.40 **Hydro Radial** 3500/01 Software - Version 3.80 Vibration 3500/02 Software - Version 2.51 **Applications** 3500/03 Software - Version 1.51 3500/46M Module Firmware -Version 2.02 3500/01 Software - Version 2.70 Multimode applications that will use hardware contacts to change 3500/02 Software - Version 2.21 monitor modes require: 3500/03 Software - Version 1.22 3500/46M Module Hardware -Revision S Multimode I/O modules.

Multimode applications that will use software commands to change monitor modes require:

3500/22 Module Firmware – Version 1.32

3500/92 Module Firmware – Version 1.16

Multimode applications incorporating the 3500/94 Display require:

3500/22 Module Firmware – Version 1.60

3500/94 Module Firmware – Version 2.30

Applications that require full multimode support from System1 require:

System1* Software - Version 6.0

3500/22 Module Firmware – Version 1.32

A multimode recorder ET block must be used with an external termination multimode I/O module, and a 129525 signal cable is used to connect these components. The ET block provides recorder outputs and mode inputs.

External Termination Blocks cannot be used with Internal Termination I/O Modules.

When ordering I/O Modules with External Terminations, the External Termination Blocks and Cables must be ordered separately.

Hydro SEW Applications

3500/46M Module Firmware – Revision 4.10

3500/01 Software - Version 3.93

3500/02 Software - Version 2.52

3500/03 Software - Version 1.52

Ordering Information

Hydro Monitor 3500/46-AXX-BXX

A: I/O Module Type

- **0 1** Prox/Velom I/O Module with Internal Terminations
- **0 2** Prox/Velom I/O Module with External Terminations
- 0 3 Multimode Prox/Velom I/O Module with Internal Terminations
- 0 4 Multimode Prox/Velom I/O Module with External Terminations
- 0 5 Multimode Positive Input I/O Module with Internal Terminations
- 0 6 Multimode Positive Input I/O Module with External Terminations
- **B:** Agency Approval Option
 - 00 None
 - 01 CSA/NRTL/C
 - **0 2** ATEX/CSA (Class 1, Zone 2)

Note: Agency Approval Option B 02 is only available with Ordering Options A 01, A 03, A 04, A 05, and A 06.

External Termination Blocks 125808-08

Prox/Velom External Termination Block (Euro Style connectors).

125808-11

Multimode Prox/Velom External Termination Block (Euro Style connectors).

125808-12	Multimode Positive Input External Termination Block (Euro Style connectors).	B: Assembly Instructions 0 1 Not assembled. 0 2 Assembled.
125808-13	Multimode Recorder Output and Mode Input External Termination Block (Euro Style connectors).	Recorder Output to External Termination (ET) Block Cable (Non-Multimode) 129529-AXXXX-BXX A: Cable Length
128702-01 128015-08	Recorder External Termination Block (Euro Style connectors).	 0005 5 feet (1.5 metres) 0007 7 feet (2.1 metres) 0010 10 feet (3 metres) 0025 25 feet (7.5 metres) 0050 50 feet (15 metres) 0100 100 feet (30.5 metres)
128015-11	Prox/Velom External Termination Block (Terminal Strip connectors). Multimode Prox/Velom External	B: Assembly Instructions 0 1 Not assembled. 0 2 Assembled.
	Termination Block (Terminal Strip connectors).	Spares 176449-06
128015-12	Multimode Positive Input External Termination Block (Terminal Strip connectors).	3500/46M Hydro Monitor. 144403-01 3500/46M Monitor Manual.
128015-13	Multimode Recorder Output and Mode Input External Termination Block (Terminal Strip connectors).	140471-01 Prox/Velom I/O Module with Internal Terminations. 140482-01
128710-01	Recorder External Termination Block (Terminal Strip connectors).	Prox/Velom I/O Module with External Terminations. 169459-01
External Termination Cables		Multimode Prox/Velom I/O Module with Internal Terminations.
Transducer (XCDR) to External Termination (ET) Block Cable 129525-AXXXX-BXX A: Cable Length		169459-02 Multimode Prox/Velom I/O Module with External Terminations.
A. Cubic Leligi	0005 5 feet (1.5 metres) 0007 7 feet (2.1 metres) 0010 10 feet (3 metres) 0025 25 feet (7.5 metres) 0050 50 feet (15 metres) 0100 100 feet (30.5 metres)	169715-01 Multimode Positive Input I/O Module with Internal Terminations.

169715-02 00580434

Multimode Positive Input I/O Module with External

Terminations.

00561941

00580432

Prox/Velom and Multimode Prox/Velom I/O Module ten-pin

connector shunt.

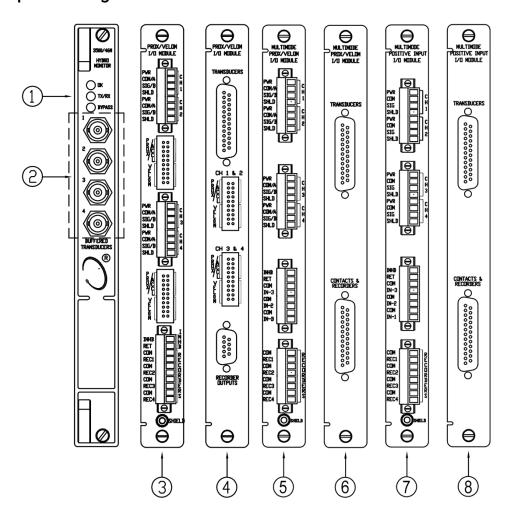
Euro Style connector header, 8 pin, for use on I/O modules with internal terminations.

internal termination

Euro Style connector header, 10 pin, for use on I/O modules with

internal terminations.

Graphs and Figures



- 1. Status LEDs
- 2. Buffered Transducer Outputs
- 3. Prox/Velom I/O Module with Internal Terminations
- 4. Prox/Velom I/O Module with External Terminations
- 5. Multimode Prox/Velom I/O Module with Internal Terminations
- 6. Multimode Prox/Velom I/O Module with External Terminations
- 7. Multimode Positive Input I/O Module with Internal Terminations
- 8. Multimode Positive Input I/O Module with External Terminations

Figure 1: Front and rear view of the Hydro Monitor

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